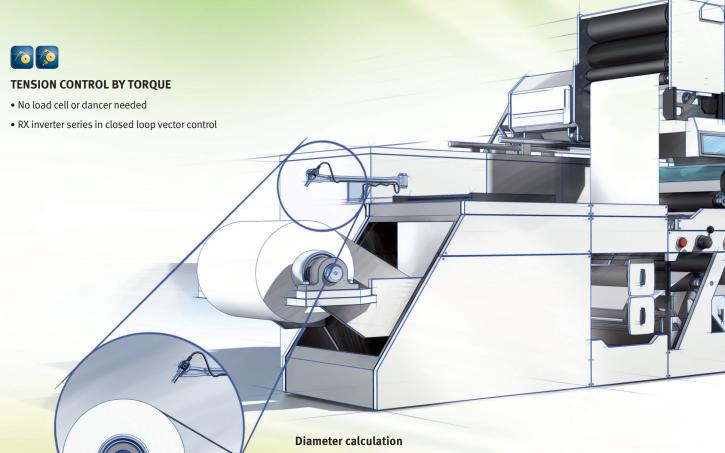




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Inverter Application Software...

Based on OMRON's experience in winder applications, the RX inverter offers four times faster torque control loop. In addition to this torque control loop improvement, the solution includes dedicated application functions such as diameter calculation without sensor, winder/unwinder bidirectional modes and tension control by either torque or PID. The built-in programming functionality also offers a set of software libraries for your winder application.



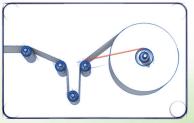
- With or without diameter sensor
- Both Torque control and PID control

1010

TENSION CONTROL BY PID

- Load cell or dancer is needed
- MX2 & RX inverter series can work in this mode





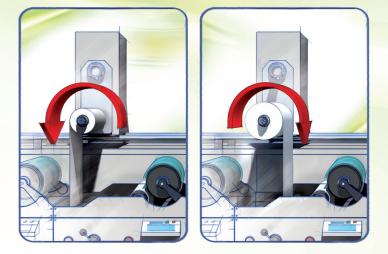
DANCER

LOAD CELL



Winder & Unwinder mode

- Both can work in forward or reverse
- Both are available in torque and PID tension control modes





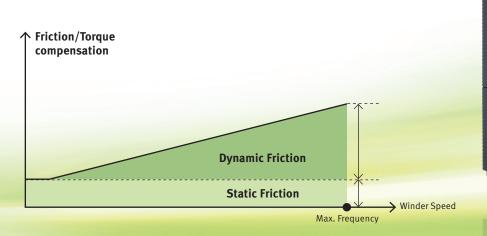
Machine loses compensation

- Static and dynamic friction compensation
- Effective tension control by Torque



Dedicated monitors

- Like diameter or final product torque reference are supported
- New monitors can be implemented based on application needs





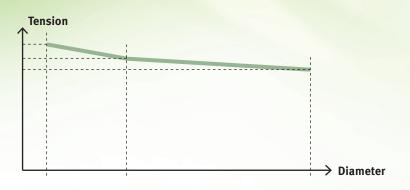
... for Winder Solutions

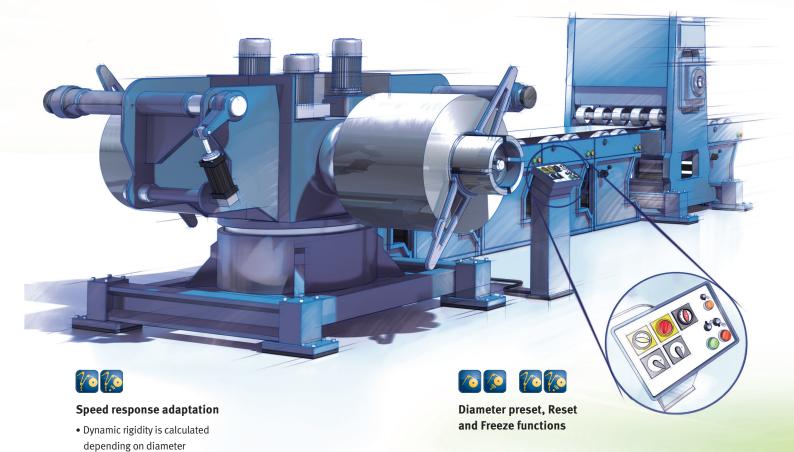
The Omron Winder Inverter Application Software Library has been developed using different functions for tension control by torque or PID regulation. Additionally, CX-Drive Programming enables existing functions to be adapted to customers' needs. New functions can also be created resulting in exclusive, tailor-made solutions. Customers may also develop their own application software with the CX-Drive Programming open tool.



Tension correction by diameter

The Taper function compensates for the non-linear effects of winding tension causing telescoping and excessive crushed rolls. These effects may appear even with the correct diameter, PID regulation and/ or correct torque set point calculation. Taper provides a tension compensation curve based on diameter







RX INVERTER

- Supports winder Tension control by:
- Torque in closed loop vector control
- PID in open loop & closed loop vector control



MX2 INVERTER

- Supports winder Tension control by:
- PID in open loop vector control

APPLICATION SOFTWARE LIBRARIES

Benefit from using Omron's Inverter Application Software Library which provides solutions for cranes, winders, positioning, water and energy as well as other areas which will be launched in the future. Omron's inverter **application software can be customised to meet specific customer needs...**



RX Inverter



- Power range up to 132 kW
- Sensor-less and closed-loop vector control
- High starting torque in open loop (200% at 0.3 Hz)
- Full torque at 0 Hz in closed-loop
- Double rating VT 120%/ 1 min and CT 150%/1 min
- Built-in application functionality: ELS (Electronic Line Shaft), brake control, load over speed control

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-phase: 3G3RX			A2004	A2007	A2015	A2022	A2037	A2055	A2075	A2110	A2150	A2185	A2220	A2300	A2370	A2450	A2550
aabla matar 10 k	w	at CT	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
CODIE INOLOI 4P K	vv	at VT	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75
	200 V	at CT	1.0	1.7	2.5	3.6	5.7	8.3	11	15.9	22.1	26.3	32.9	41.9	50.2	63	76.2
Inverter	200 V	at VT	1.3	2.1	3.2	4.1	6.7	10.4	15.2	20	26.3	29.4	39.1	49.5	59.2	72.7	93.5
capacity KVA	240 V	at CT	1.2	2.0	3.1	4.3	6.8	9.9	13.3	19.1	26.6	31.5	39.4	50.2	60.2	75.6	91.4
	240 V	at VT	1.5	2.6	3.9	5.0	8.1	12.4	18.2	24.1	31.5	35.3	46.9	59.4	71	87.2	112.2
Dated autout a	secont (A)	at CT	3.0	5.0	7.5	10.5	16.5	24	32	46	64	76	95	121	145	182	220
кател оптрлт ст	Inenii (A)	at VT	3.7	6.3	9.4	12	19.6	30	44	58	73	85	113	140	169	210	270
	cable motor 4P k Inverter capacity KVA	cable motor 4P kW 200 V	cable motor 4P kW at CT at VT t VT Inverter capacity KVA 200 V 240 V at CT at VT at VT at VT at CT Rated output current (A) at CT	$ \begin{array}{c} \mbox{adel motor 4P kW} & \mbox{at CT} & 0.4 \\ \mbox{at VT} & 0.75 \\ \mbox{at VT} & 0.75 \\ \mbox{at VT} & 0.75 \\ \mbox{at VT} & 1.0 \\ \mbox{at VT} & 1.3 \\ \mbox{at VT} & 1.2 \\ \mbox{at VT} & 1.5 \\ \mbox{at ex VT} & 1.5 \\ \mbox{at ex VT} & 3.0 \end{array} $	at CT 0.4 0.75 at VT 0.75 1.5 at VT 0.75 1.5 Inverter capacity KVA 200 V at CT 1.0 1.7 240 V at CT 1.2 2.0 1.1 2.1 240 V at CT 1.2 2.0 1.5 2.6 Rated output current (A) at CT 3.0 5.0	$ \begin{array}{c} \mbox{able motor 4P} \mbox{ km} \\ \mbox{cable motor 4P} \mbox{ km} \\ \mbox{cable motor 4P} \mbox{ km} \\ \mbox{cable motor 4P} \mbox{ km} \\ \mbox{ lnverter} \\ \mbox{capacity KVA} \\ \mbox{ lnverter} \\ \mbox{ capacity KVA} \\ \mbox{ lnverter} \\ \mbox{ capacity KVA} \\ \mbox{ lnverter} \\ \mbox{ lnverter} \\ \mbox{ capacity KVA} \\ \mbox{ lnverter} \\ \mbox{ lnverter} \\ \mbox{ capacity KVA} \\ \mbox{ lnverter} \\$	at CT 0.4 0.75 1.5 2.2 at CT 0.75 1.5 2.2 3.7 Inverter capacity KVA at CT 1.0 1.7 2.5 3.6 at CT 1.2 2.0 3.1 4.3 at CT 1.5 2.6 3.9 5.0 at CT 3.0 5.0 7.5 10.5	$ \begin{array}{c} \mbox{able motor 4P} \\ able mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ able mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ able mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ able mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ \mbox{blue motor 4P} \\ \mbox{able motor 4P} \\ able mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ \mbox{bale motor 4P} \\ bale mot$	$ \begin{array}{c} \mbox{able motor 4P} \\ \mbox{bale motor 4P} \\ bale mot$	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	at C1 0.4 0.75 1.5 2.2 3.7 5.5 7.5 11 15 18.5 2.2 3.0 3.7 at V1 0.75 1.5 2.2 3.7 5.5 7.5 11 15 18.5 2.2 3.0 3.7 Inverter at C1 1.0 1.7 2.5 3.6 5.7 11 15 18.5 2.2 3.0 3.7 at C1 1.0 1.7 2.5 3.6 5.7 8.3 11 15.9 2.21 2.63 3.2.9 41.9 5.0.2 at C1 1.0 1.7 2.5 3.6 5.7 8.3 11 15.9 2.21 2.63 3.2.9 41.9 5.0.2 at C1 1.0 1.7 2.5 3.6 5.7 8.3 11 15.9 2.21 2.6.3 3.2.9 41.9 5.0.2 3.0 3.1	$ \begin{array}{c c c c c c c c c c c c c c c c c c c $

400	class
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Three	-phase: 3G3RX			A4004	A4007	A4015	A4022	A4040	A4055	A4075	A4110	A4150	A4185	A4220	A4300	A4370	A4450	A4550	B4750	B4900	B411K	B413K
May appli	aabla matar 40 l	AM.	at CT	0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132
Max. appli	cable motor 4P k	(W	at VT	0.75	1.5	2.2	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160
	100.11	at CT	1.0	1.7	2.5	3.6	6.2	9.7	13.1	17.3	22.1	26.3	33.2	40.1	51.9	63	77.6	103.2	121.9	150.3	180.1	
	Inverter	400 V	at VT	1.3	2.1	3.3	4.6	7.7	11	15.2	20.9	25.6	30.4	39.4	48.4	58.8	72.7	93.5	110.8	135	159.3	200.9
Output		400 V	at CT	1.2	2.0	3.1	4.3	7.4	11.6	15.8	20.7	26.6	31.5	39.9	48.2	62.3	75.6	93.1	128.3	146.3	180.4	216.1
characteristics		40U V	at VT	1.5	2.5	4.0	5.5	9.2	13.3	18.2	24.1	30.7	36.5	47.3	58.1	70.6	87.2	112.2	133	162.1	191.2	241.1
		at CT	1.5	2.5	3.8	5.3	9.0	14	19	25	32	38	48	58	75	91	112	149	176	217	260	
	Rated output c	uiteilt (A)	at VT	1.9	3.1	4.8	6.7	11.1	16	22	29	37	43	57	70	85	105	135	160	195	230	290

Selection guide: KPP_RX_EN_INT

SOFTWARE TOOL

• CX-Drive with Drive Programming functionality



*Note: Please contact your OMRON representative for detailed specifications and ordering information.

MX2 Inverter





- Power range up to 15 kW
- Torque control in open loop
- 200% starting torque (at 0.5 Hz)
- Double rating VT 120%/1 min and CT 150%/1 min
- Models with IP54 housing protection
- 24 VDC backup supply for control board and communication
- Built-in application functionality (i.e. Brake control)

Inverter

Software*

200 V class													
	Single-phase: 3G3	3MX2	B001	B002	B004	B007	B015	B022	-	-	-	-	-
	Three-phase: 3G3	3MX2	2001	2002	2004	2007	2015	2022	2037	2055	2075	2110	215
Moto	r kW	For VT setting	0.2	0.4	0.55	1.1	2.2	3.0	5.5	7.5	11	15	18.
MOLO	I KW	For CT setting	0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15
		200 VT	0.4	0.6	1.2	2.0	3.3	4.1	6.7	10.3	13.8	19.3	23.
Output	Inverter	200 CT	0.2	0.5	1.0	1.7	2.7	3.8	6.0	8.6	11.4	16.2	20
	capacity kVA	240 VT	0.4	0.7	1.4	2.4	3.9	4.9	8.1	12.4	16.6	23.2	28.
characteristics		240 CT	0.3	0.6	1.2	2.0	3.3	4.5	7.2	10.3	13.7	19.5	24
	Rated out	1.2	1.9	3.5	6.0	9.6	12.0	19.6	30.0	40.0	56.0	69	
	Rated out	put current (A) at CT	1.0	1.6	3.0	5.0	8.0	11.0	17.5	25.0	33.0	47.0	60
400 V class	Three-phase: 3G3	3MX2	4004	4007	4015	4022	2 403	30 40)40	4055	4075	4110	415
		For VT setting	0.75	1.5	2.2	3.0	4.	J 5	i.5	7.5	11	15	18.5
Motor kW For CT setting													
MOLL		For CT setting	0.4	0.75	1.5	2.2	3.	3 4	1.0	5.5	7.5	11	15
MOL		For CT setting 380 VT	0.4	2.6	1.5	2.2	3.0		1.0 7.3	5.5 11.5	7.5 15.1	11 20.4	15 25.0
Mole	Inverter							7 7					
Output	Inverter capacity kVA	380 VT	1.3	2.6	3.5	4.5	5.	7 7 7 6	7.3	11.5	15.1	20.4	25.0 20.4
		380 VT 380 CT	1.3 1.1	2.6	3.5 3.1	4.5	5.	7 7 7 6 3 9	7.3 5.0	11.5 9.7	15.1 11.8	20.4 15.7	25.0
Output	capacity kVA	380 VT 380 CT 480 VT	1.3 1.1 1.7	2.6 2.2 3.4	3.5 3.1 4.4	4.5 3.6 5.7	5. 4. 7.:	7 7 7 6 3 9 9 7	7.3 5.0 9.2	11.5 9.7 14.5	15.1 11.8 19.1	20.4 15.7 25.7	25.0 20.4 31.5

SOFTWARE TOOL

• CX-Drive with Drive Programming functionality

APPLICATION LIBRARIESWinderWaterHoist & LiftTextileEnergyImage: Display ConstrolImage: Display Constrol<t

*Note: Please contact your OMRON representative for detailed specifications and ordering information.

OMRON

Automation Systems

- Programmable logic controllers (PLC) Human machine interfaces (HMI) Remote I/O
- Industrial PC's Software

Motion & Drives

• Motion controllers • Servo systems • Inverters • Robots

Control Components

- Temperature controllers Power supplies Timers Counters Programmable relays
- Digital panel indicators Electromechanical relays Monitoring products Solid-state relays
- Limit switches Pushbutton switches Low voltage switch gear

Sensing & Safety

- Photoelectric sensors Inductive sensors Capacitive & pressure sensors
- Cable connectors Displacement & width-measuring sensors Vision systems
- Safety networks Safety sensors Safety units/relay units Safety door/guard lock switches

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