

# Sysmac: A fully integrated platform

One connection - One software - One machine controller

# **FACTORY AUTOMATION**

HMI · Programming · DB connection · IT systems



# **MACHINE CONTROL**

Servo · Inverter · I/O · Safety · Vision · Robotics · Sensing



# Omron provides tailored solutions

# Flexible and integrated production business models

In today's globalized manufacturing environment, diverse and complex challenges arise and need to be overcome. The global market rapidly changes, and manufacturing companies are under increasing pressure to supply products in a timely manner that satisfy a wide variety of consumer needs. Omron industrial automation makes efficient, flexible and cost effective manufacturing possible.



### **Innovation**

- New technology for smart manufacturing
- Collaboration between humans and machines
- Environmentally safe products



# **Productivity**

- Integrated systems for optimized manufacturing
- Production data available in real-time
- In-line quality inspection: zero defects



### Flexibility

- Quick product changeovers
- · Openness and third party connectivity
- Scalable systems for optimum solutions



### Reliability

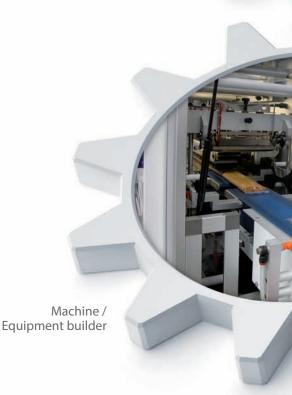
- Non-stop processes, 24/7 operation
- Extended product lifecycle



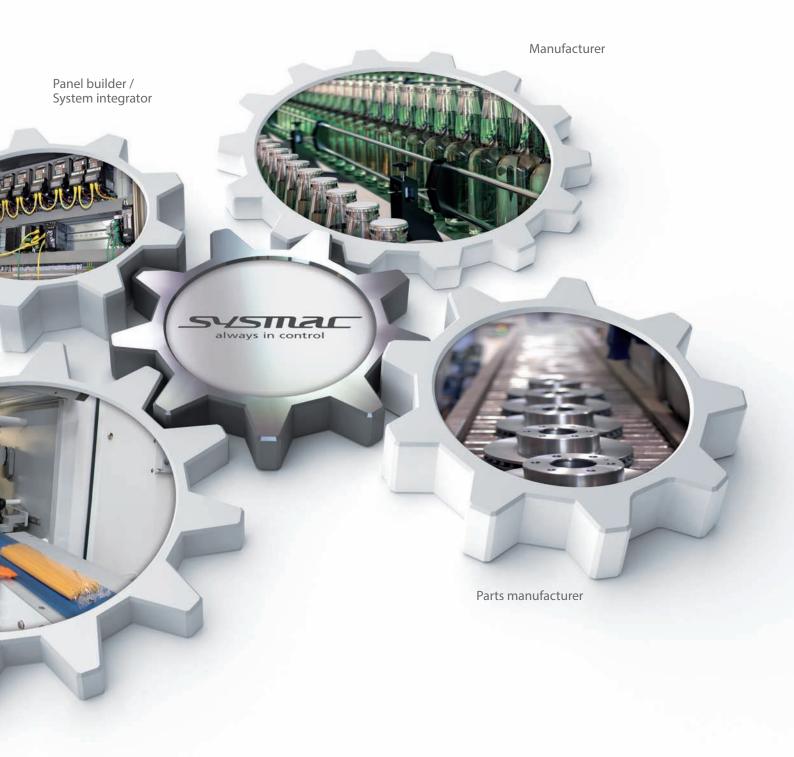
### Globalization

- Products meet global standards
- Local support for training, repairs and spare-parts supply
- Engineering environment compliance with global standards

✓ Through automation, Omron supports the advancement of manufacturing and contributes to a sustainable society by providing environmentally safe products



The Sysmac technology platform ensures a flexible and integrated production business model



# Sysmac: A fully integrated platform

# **Integration and Functionality**

Sysmac is an integrated automation platform dedicated to providing complete control and management of your automation plant. At the core of this platform, the Machine Controller series offers synchronous control of all machine devices and advanced functionality such as motion, robotics and database connectivity. This multidisciplinary concept allows you to simplify solution architecture, reduce programming and optimize productivity.

### One Machine Controller

Complete integration of motion and logic sequence



FACTORY AUTOMATION

MACHINE CONTROL

Machine Automation Controller / Industrial PC with Sysmac Machine Control



# Motion



- Motion Control: Integrated within the IDE, and operating in real-time
- Standard PLCopen Function Blocks plus Omron generated motion FB's
- Direct Synchronous control for Position, Speed and Torque

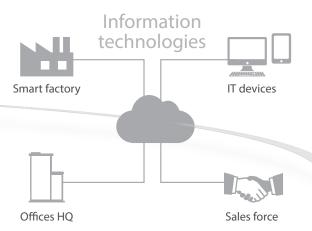




- The simplest way to integrate safety improves productivity and safety
- The PLCopen® safety FB's simplify and accelerate the development process

 One Integrated Development Environment software for Configuration, Programming, Simulation and Monitoring





# **Information**



- roal time with Databas
- Sysmac communicates in real-time with Databases such as SQL
- Secure Data: In the event of a server going down or losing communications, data is automatically stored in internal memory
- Sysmac operates with Databases at high speed [1000 table element/ 100 ms] ensuring realistic Big Data Processing to improve productivity and aid predictive maintenance etc.

# ✓ Integrated Automation Control:

The Sysmac platform is scalable and provides the performance and functionality for a wide range of solutions from simple machines through to manufacturing cells

# Vision



- Higher resolution images available without increasing the vision processing time
- Shape search technology: Provides more stable and accurate object detection for Pick & Place projects





 One controller integrates two different types of engines, one based on cyclic scanning (PLC feature) and another based on procedural programming (robot feature), providing direct control of robots

# **Sensing**

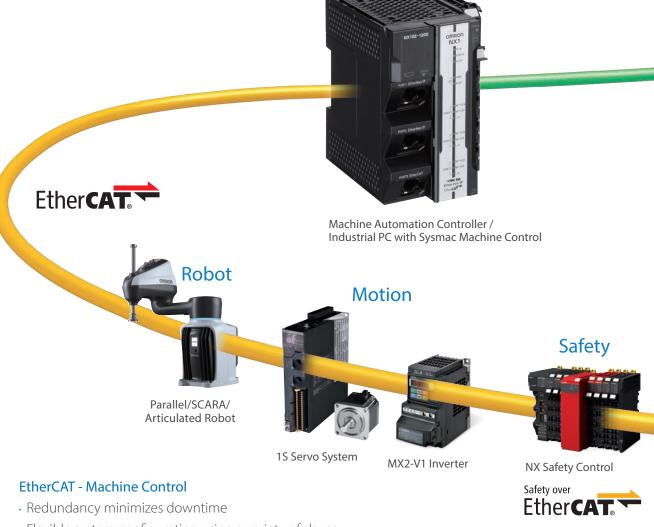


- Full control of the process parameter setting and predictive maintenance functions
- High precision detection and positioning data synchronized on the network

# One Connection

### Seamless machine control and factory automation

One machine control through one connection and one software is how we define the Sysmac automation platform. The Machine Automation Controller integrates logic, motion, safety, robotics, vision, information, visualization and networking under one software: Sysmac Studio. This one software provides a true Integrated Development Environment (IDE) that also includes a custom 3D motion simulation tool. The machine controller comes standard with built-in EtherCAT and EtherNet/IP. The two networks with one connection purpose and integrated safety are the perfect match between fast real time machine control and data plant management.



- · Flexible system configuration using a variety of slaves
- · Fast and precise: Fastest cycle time of 125 μs, synchronization with 1 μs jitter
- · 512 slaves
- Embedded in Omron servo drive, inverter, I/O, Safety, Vision and Sensing
- · Uses standard STP Ethernet cable with RJ45 connectors
- · One connection using Safety over EtherCAT (FSoE) protocol





Database





SCADA/MES/ERP



# HMI



NA /Soft-NA Programmable Terminal

# Software













# Ethernet - Factory Automation

- · Peer-to-Peer controller communication
- · Interface with Sysmac Studio , NA HMI or SCADA software
- Database connection for Microsoft SQL Server, Oracle, IBM DB2, MySQL and Firebird
- FTP server
- · Safety integrated via CIP Safety
- · Secure cloud connection by MQTTS communication

# Vision FH FH7

# Sensing



ZW-8000/7000/5000 Confocal Fiber Displacement Sensor



N-Smart Fiber/Laser/Contact Sensor IoT Status Monitoring Amplifier



NX I/O

IO-Link

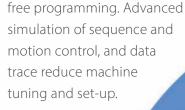
IO-Link Sensor

EtherCAT.

# One Software

# One Integrated Development Environment Software

Created to give you complete control over your automation system, Sysmac Studio integrates configuration, programming and monitoring. Graphics-oriented configuration allows quick set-up of the controller, field devices and networks while machine, motion, and safety programming based on IEC standard and PLCopen® Function Blocks for Motion Control and Safety cuts programming time. Smart Editor with On-line debugging helps quick and error



# Design

# **Reusable programs**

### Programming with variables



One Integrated Development Environment software Sysmac Studio is fully compliant with the open standard IEC 61131-3. Programming with variables eliminates the need to learn the internal memory map of the PLC and allows the programs to be reused.

# Maintenance

# **Highly efficient maintenance**

### Troubleshooting



Troubleshooting in the Sysmac Studio and NA Programmable Terminal can manage errors across the entire system including the controller. You can check details of errors and solutions without reading manuals.

<sup>\*1.</sup>This function can be used by applying the Team Development Option to Sysmac Studio version 1.20 or higher Project version control function is supported by CPU Unit version 1.16 or later.

 $<sup>^{*}</sup>$ 2. Available with the Sysmac Studio 64-bit version. 3D CAD data supports STEP/IGES.

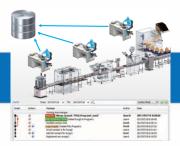


# Collection of software functional components Sysmac Library

Packed with Omron's rich technical know-how, the Function Blocks in the Sysmac Library for advanced applications and motion control cut programming time.

# **Development by** multiple developers

### Project version control function\*1



When you develop a project at the same time as your colleagues, the Sysmac Studio combined with the version control system (Git™) merges changes automatically and resolves conflicting changes. This makes merging easier and faster. You can even revert to the previous revision after graphically comparing the current project with a previous one.

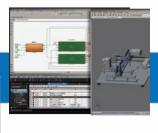
# For advanced machine control

### Motion programming



Advanced motion control applications can be created quickly just by combining PLCopen® **Function Blocks for** Motion Control.

### | Model-Based design



Complex feedback control that is designed with MATLAB®/Simulink® can be imported into programs.

# MathWorks



# **Efficient designing linked to** electrical CAD

### AutomationML import function NEW **Electrical CAD**

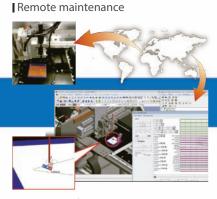


Circuit diagrams designed using electrical CAD data (e.g., unit configurations and signal lines) can be imported to the Sysmac Studio and automatically reflected in unit configurations and settings and allocated variables. Seamless and accurate setup using electrical CAD design data speeds up the engineering process and improves design efficiency.



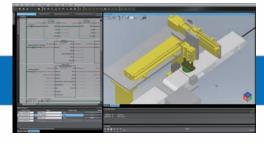
# Verifification

# Fast system debugging



Movement of the machine connected online can be displayed on the CAD in real time, and movement can also be reproduced from the trace data. Maintenance and troubleshooting can be performed in remote locations.

Virtual mechanical debugging



# Enhanced by 3D simulation option\*2

Use only the Sysmac Studio with loaded 3D CAD data\*2 for 3D simulations. Operation of a control program can be verified in a virtual environment, improving program accuracy during design and reducing rework during verification using physical devices.



Debugging in conjunction with a third-party simulator is possible.



# One Machine Controller

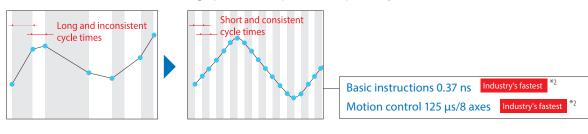
# NJ/NX/NY Machine Automation Controller

# Powerful, yet easy to configure

The NJ/NX/NY Controller is at the heart of the Sysmac platform. One integrated controller is designed to meet extreme requirements in terms of logic sequence and motion control speed and accuracy. Standard programming and open networks make it easy to build your automation system.

### High-speed, high-precision control\*1

Architecture based on Intel® Core™ processor significantly speeds up the execution of instructions (basic instructions 0.37 ns, math instructions for Long Real Data 3.2 ns). Command values to send to servomotors and stepper motors can be updated as fast as every 125 µs. This enables smooth cam motion and high-precision interpolation and phase adjustment between axes.



# Complete integration of motion and logic





Integrated safety into machine control\*3

The controller integrates safety control into machine control in lines that require fast cycle times. It also integrates two different open networks: EtherNet/IP for safety control in production lines and EtherCAT for safety control in machines.

- \*1. Performance of NX701-1 □ 00
- \*2. Based on Omron investigation in February 2015.
- \*3. Performance of NX502- \( \sqrt{1} \sqrt{1} \sqrt{1} \sqrt{1} \sqrt{1} \sqrt{2} \sqrt{1} \sqrt{2} \sqrt{1} \sqrt{2} \sqrt{1} \sqrt{2} \
- \*4. Database connection CPU unit: NX502-1 \( \Bigcirc 00/\ NX102- \( \Bigcirc 20/\ NJ \( \Bigcirc 01- \Bigcirc 20 \)
- \*5. Performance of NX701-1 \( \square\) \( \
- \*6. Performance of NX502-1 \bigcup 00/NX102- \bigcup \bigcup \bigcup /NX1P2- \bigcup \bigcup \bigcup
- \*7. Performance of NX502-1 \\_ 00/NX102- \\_ \\_ \\_

# Fast machine data storage in database\*4

The controller connects directly to a database without the need for a gateway. The special instructions allow easy access to the database.

Real-time data collection enables productivity improvement, predictive maintenance, and quality traceability.

### Secure host connection

OPC UA is an IEC communication protocol which is listed as a recommendation for Industrie 4.0 and PackML. The controller comes equipped with an OPC UA server interface and provides a secure connection to IT systems such as MES and ERP.\*5 The controllers provides a easily and secure connection to the cloud by using MQTT Communications Library.\*6







NX7

### Supported database

- Microsoft SQL server
- Oracle Database
- IBM DB2
- MySQL
- PostgreSQL
- Firebird

### Standard programming

- Fully conforms with IEC 61131-3 standards
- · PLCopen Function Blocks for Motion Control















# Collection of software functional components Sysmac Library

- FB library option for advanced applications (vibration suppression, temperature control, motion control...)
- High quality products with reliable global support



# Drive machine innovation by increasing speed

# Case 1: High-speed alignment and vibration-free handling

# **Problems**

- 1. Precisely stacking many sheets increases cycle time because retries caused by mechanical errors increase positioning time.
- 2. Vibration settling time is required when high-speed handling is stopped. Speed must be reduced to suppress vibration.

# 1. High-speed, high-precision alignment system

The FH Vision System provides the Shape Search function for fast and accurate shape recognition and Visual Feedback that feeds back the current position to control the motor in every measurement cycle. These increase alignment speed without sacrificing accuracy.

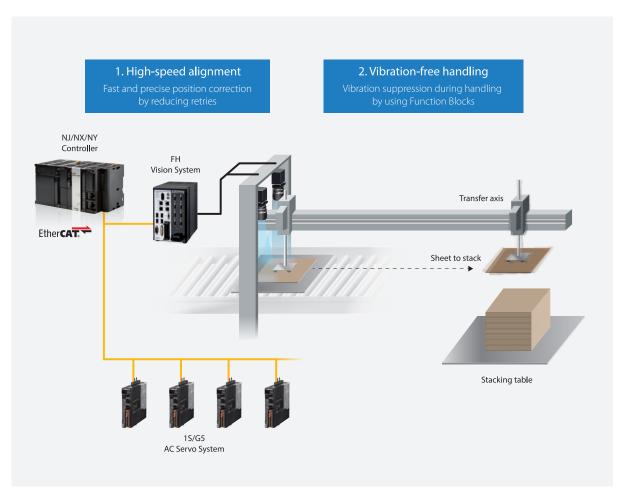


### 2. Software functional components for vibration suppression

The Vibration Suppression Library facilitate programming for high-speed handling while suppressing vibration. Waiting time is reduced, and positional accuracy is increased.



Vibration Suppression Library



# and precision and maximizing uptime

# Case 2: Data utilization improves yield

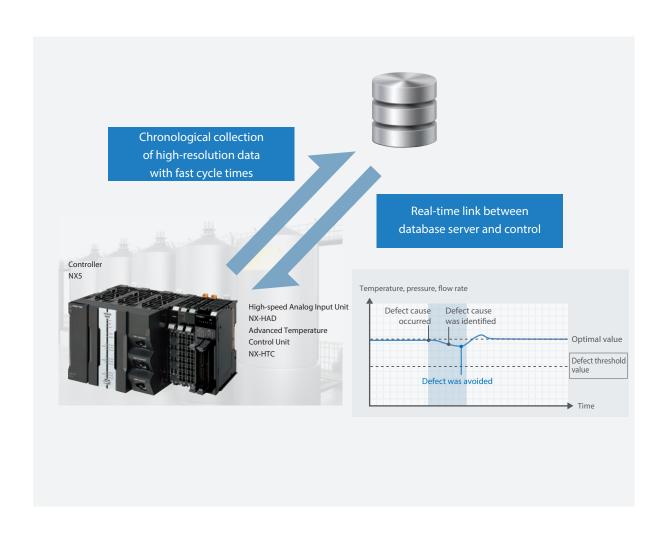
# **Problems**

The amount of equipment data to find optimal processing conditions is so large that it takes time to transfer data and feed back analysis results. This results in low yield.

### Real-time feedback increases yield

With approximately four times the data transfer capability of the NJ5 Series, NX5 can transfer all of the high-resolution data to a database at high speeds.

NX5 also reflects results of database analysis in processing conditions in real time, contributing to defect prevention and yield improvement.



# Case 3: Increase equipment availability through integrated safety

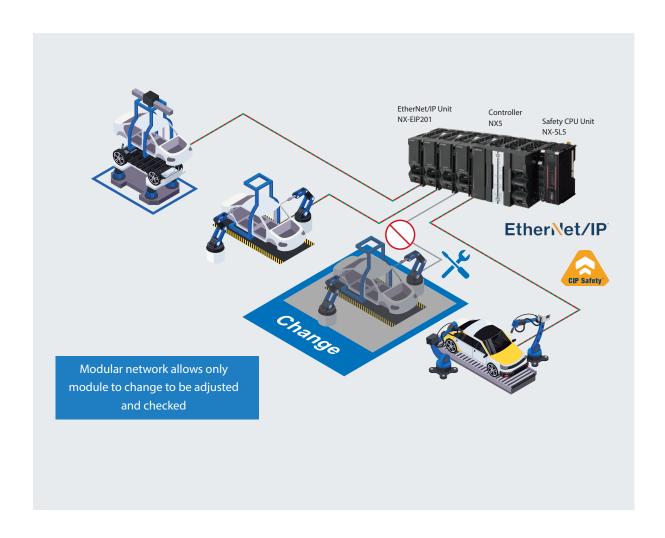
# Problems

- 1. Manufacturers need to cope with rapid demand changes by building flexible equipment.
- 2. Network power supply must be turned off for changing a process because safety communications are configured within the same network segment. This results in long lead time.

# Safety integrated controller enables modular safety network configuration

Control and safety integrated controller and up to eight separate CIP Safety networks enable you to modularize network configurations including safety as well as software and hardware.

The localized process to change can be adjusted and checked without stopping the entire production line, significantly reducing lead time for line changes.



# Case 4: Redundancy minimizes downtime

# Problems

- 1. It takes time to recover from an unexpected production line stop, significantly reducing uptime.
- 2. The safety system stops the entire line due to disconnection or other causes even when there is no danger.

### **Cable Redundancy**

Even if a part of the EtherCAT network is disconnected, Cable Redundancy provides continuous connectivity. This function allows you to fix disconnection without stopping the machines and production line where one controller provides both machine and safety control.

The line stops only when operators are in danger, which ensures safety.



# Controller

# NX5

# Machine Automation Controller CPU Unit

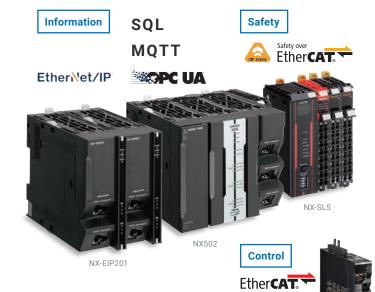
Integrated control, information, and safety brings a new level of speed to manufacturing sites

# Control for fast-cycle, high-precision processing

- $\cdot$  Controls 32 axes with cycle time of 250  $\mu s$
- · Used motion control servo axes: 64, 32, 16 axes
- · Program capacity: 80 MB
- · Memory capacity for variables: 260 MB\*1

# **Diverse information utilization**

- · SQL functionality for reliable, rapid, and easy direct access
- $\cdot$  Use of MQTT for data collection directly to cloud
- · OPC UA functionality for secure connection to MES and ERP
- · 10 x 1 Gbps ports for high-speed, high-capacity communications\*2



# 2 different open networks for safety control of production lines and machines

Fail Safe over EtherCAT (FSoE)

- · High speed and high reliability with redundancy, suitable for safety control in machine
- $\cdot$  254 connections for large and flexible production line

Common Industrial Protocol Safety (CIP Safety)

- · High scalability, suitable for safety control across production line
- · Up to 8 separate networks for network modularization

<sup>\*2.</sup> Four NX-EIP201 EtherNet/IP Units per NX5

# NX1

# Machine Automation Controller CPU Unit

Helps improve production efficiency of small systems

# Integration of control and information into a miniaturized housing

- · 3 industrial Ethernet ports and a power supply housed in a compact design with a width of 66 mm
- · Multicore processor and OPC UA functionality



# NX7

# Machine Automation Controller CPU Unit

Offers exceptional speed without compromising on reliability

### High-speed, high-precision control of large-scale systems

- · Motion control axes: 256 axes
- · Instruction execution times (LD instructions) 0.37 ns
- · Controls 8 axes with cycle time of 125 μs

# NJ501-R

# Robot integrated CPU unit

Integration of logic, motion, Omron Robot and kinematics in one CPU

# **Industry first\*:**

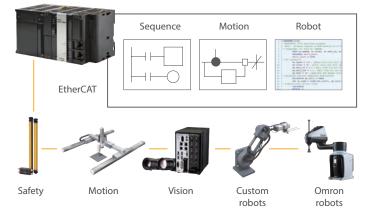
# **Integrated control of different engines**

· Integrates two different types of engines, one based on cyclic scanning (PLC control) and another based on procedural programming (robot control)

# Collection of trully useful data

- · Synchronizes control of robots, motion, vision sensors and other devices on an EtherCAT network, ensuring data concurrency
- · Direct access to a database and real-time data collection

Robot integrated CPU unit NJ501-R



# Sysmac Family Controller

Series				N:	X Series	
Product na	me		NX701 CPU Units	NX502 CPU Units	NX102 CPU Units	NX1P2 CPU Units
Model		NX701-□□□□	NX502-□□□□	NX102-□□□□	NX1P2-□□□□	
Appearance		(NX701-1 00)	PC UA	PC UA		
	CPU Unit features		Ideal for large-scale, fast, and highly-accurate control with up to 256 axes.	Ideal for large-scale, fast, and highly-accurate control with up to 64 axes. Used with NX-EIP201 to configure up to 10 EtherNet/IP networks.	Compact controller with up to 8 axes motion control.	Compact controller with up to 4 axes motion control, up to 4 axes single-axiscontrol, and built-in I/O.
	Instruction	LD instructions	0.37 ns or more	0.53 ns or more	3.3 ns	3.3 ns
	execution times	Math instructions (for long real data)	3.2 ns or more	3.3 ns or more	70 ns or more	70 ns or more
	Program ca	pacity	80 MB	80 MB	5 MB	1.5 MB
Specifications	Variable capacity		4 MB: Retained during power interruptions 256 MB: Not retained during power interruptions	4 MB: Retain attributes 256 MB: No Retain attributes	1.5 MB: Retained during power interruptions 32 MB: Not retained Zuring power interruptions	32 KB: Retained during power interruptions 2 MB: Not retained during power interruptions
	I/O capacity/maximum number of configuration Units (Expansion Racks)		_	— Up to 63 NX I/O Units connectable	— Up to 32 NX I/O Units connectable	Built-in I/O: 40 points max. Up to eight NX I/O Units connectable
	Number of	motion axes	128, 256	16, 32, 64	0, 2, 4, 8 *1	0, 2, 4 *1
	EtherCAT sl	aves	512	256	64	16
	Number of robots	controlled	_	_	_	_
	Number of OMRON rol		_	_	_	_
	Database co	onnection	●NX701-1□20	•	●NX102-□□20	_
Functions	SECS/GEM communica	tions functions	_	_	_	_
	Numerical ( functions	Control (NC)	_	_	_	_
External mem	nory		Memory Cards	Memory Cards	Memory Cards	Memory Cards
Detailed spec	ification (Dat	asheet)	P141	P159	P130	P116

<sup>\*1.</sup> Motion control axes and 4 single-axis position control axes.

\*2. The number of robots that can be controlled depends on the number of axes used in the system.

\*3. The number of controlled axes of the MC Control Function Module is included.

				N.	J Series			
		NJ501 C	PU Units			NJ301 CPU Units	NJ101 C	PU Units
NJ501- 1⊡00	NJ501- R□□□	NJ501- 4□□□	NJ501- 1□20	NJ501-1340	NJ501-5300	NJ301-1□00	NJ101- □□00	NJ101- □□20
(NJ501-1□								
Ideal for large	e-scale, fast, and h	nighly-accurate co	ontrol with up t	to 64 axes.		Ideal for small control with up to 8 axes.	Ideal for simple	machines.
1.1 ns (1.7 ns	or less)					1.6 ns (2.5 ns or less)	3.0 ns (4.5 ns or less)	
24 ns or more	2					35 ns or more	63 ns or more	
20 MB						5 MB	3 MB	
MB: Retained during power interruptions     MB: Not retained during power interruptions					0.5 MB: Retained during power interruptions 2 MB: Not retained during power interruptions	0.5 MB: Retained interrupt 2 MB: Not retai interrupt	ions ned during pow	
2,560 points/ (3 Expansion						2,560 points/40 Units (3 Expansion Racks)	2,560 points/40 (3 Expansion Ra	
16, 32, 64				16	16 *3	4,8	0, 2	
192						192	64	
_	8 robots max. *2	8 robots max. *2	_			_	_	
_	8 robots max.	_	_			_	_	
_	● NJ501- R□20	NJ501- 4320	•	_		_	_	•
- • -					_	_		
-				_	_			
Memory Card	Memory Cards				Memory Cards	Memory Cards		
P140								

# NY series

NY5□□-1

Instruction execution times: 0.33 ns Program capacity: 40 MB Variables capacity (No retain attribute): 64 MB Number of EtherCAT slaves: 192 Number of motion axes: 16, 32, 64 Catalog: P118



# Software

# SYSMAC-SE2 Automation Software Sysmac Studio

# One software for programming, configuration, simulation and monitoring

- · One software for motion, logic sequence, safety, motion, vision and visualization
- $\cdot$  Fully compliant with open standard IEC 61131-3
- · Supports Ladder, Structured Text, and Function Block programming with a rich instruction set
- · Advanced security function with 32 digit security password



# SYSMAC-XR Sysmac Library

# Omron's control expertise changes programming

- · Advanced control such as vibration suppression and temperature control
- · High-precision control of packaging machines and actuators for servo presses
- · Productivity improvement by monitoring device operations and restoring parameters
- $\cdot$  Reduction in programming time







Series	Automation Software Sysmac Studio	Collection of software functional components Sysmac Library
Model	SYSMAC-SE2□□	SYSMAC-XR□□□
Appearance	Sysmac Studio  Autorigina Parameter  omnon	Sysmac Library
DVD	32-bit DVD [Supporting OS] Windows 7 (32/64-bit)/8.1 (32/64-bit)/10 (32/64-bit)/11 (64-bit) 64-bit DVD [Supporting OS] Windows 10 (64-bit)/11 (64-bit)	Download from http://www.ia.omron.com/sysmac_library/
License type / Library type	[Licenses for Editions] Standard Edition Vision Edition Measurement Sensor Edition NX-I/O Edition Drive Edition Safety Edition [Licenses for Options] Team Development Option 3D Simulation Option	MC Test Run Library MC Command Table Library MC Tool Box Library EtherCAT G5 Series Library EtherCAT G5 Series Library EtherCAT N-Smart Series Library Vibration Suppression Library Temperature Control Library Device Operation Monitor Library Adept Robot Control Library Weighing Control Library Weighing Control Library EtherCAT 15 Series Library Packaging Machine Library Servo Press Library Dimension Measurement Library Safety System Monitor Library High-Speed Analog Inspection Library SLMP Communications Library Visual Feedback Alignment Library MQTT Communications Library
Detailed specification	Refer to your OMRON website.	,

# Sysmac Family **I** HMI

# NA Programmable Terminal

# Make industrial machines more attractive and competitive by bringing technology to life

As part of the Sysmac automation platform, NA transforms machine data into information, shows information and controls devices based on requirements at FA manufacturing sites.





IAG – Intelligent Application Gadgets The graphics collection accelerates the development process. You can make your own collections and share them between projects.

Series		NA Series					
Feature		More than 16 million color (24 bit ful	More than 16 million color (24 bit full color) and wide screen for all models				
Appearance							
Display device		TFT LCD					
Screen size		15.4-inch widescreen	12.1-inch widescreen	9.0-inch widescreen	7.0-inch widescreen		
Number of dots (horizontal × vertical)		WXGA 1,280×800 dots					
Colors		16,770,000 colors (24 bit full colors)					
Built-in ports		2 Ethernet ports, 2 USB host ports, 1 USB slave port					
Allowable power supply voltage range		19.2 to 28.8 VDC					
Degree of protection		Front-panel controls: IP65 oil-proof type					
Memory card		SD/SDHC memory card					
Flame colors		Black, silver					
Detailed specification	Catalog V457						

Series		Soft-NA
Feature		NA functions work on Windows
		Soft-NA  Verent 6  First Compron  Omiron
OS		Windows 10 Pro Version 1903 or later 64 bit
Processor		Intel Atom® x5-E3940 equivalent or higher processor
RAM		4 GB or more
Optical disk drive		DVD-ROM drive
Detailed specification	Catalog	V457

# Motion

# R88M-1A□/R88D-1SAN□-ECT 1S Series with Safety Functionality

Higher Productivity and Safer Environment

### **Quick Installation: One Cable**

- · Power, encoder and brake in one pre-assembled cable with IP67 connector
- · Pluggable connectors for easy pre-wiring and system maintenance
- · Fast and secure screw-less push-in in all connectors

# 20 bit high resolution encoder

· No battery, no maintenance and compact size

# **Time Reduction: Integrated Programming and Testing**

- · Auto definition of I/F variables
- · Motion safety function blocks
- · Graphical GUI
- · Integrated Data Trace

# High adaptability for machine safety

- · 8 safety functions according to SIL3/PLe (STO, SS1, SS2, SOS, SLS, SLP, SDI, SBC)
- · Safety-over-EtherCAT (FsoE)







# R88M-1□/R88D-1SN□-ECT 1S AC Servo System

Improved machine design. Increased machine productivity

# **Optimized installation and commissioning tasks**

- · Cabinet size reduction: Compact servo drive with same height throughout the whole power range
- · Fast and secure screw-less push-in in control I/O connector and brake interlock connector

# 23 bit high resolution encoder

· No battery, no maintenance and compact size

### Multi-axis setup and tuning

- · Configure and monitor multiple axes in one view
- · Easy & fast parameter transfer among axes in the machine (up to 256 axes)
- · Comprehensive gain tuning

# Safety control via EtherCAT

- · EN ISO 13849-1(Cat.3 PLd)
- · EN61508(SIL2), EN62061(SIL2)
- · EN61800-5-2(STO)







Appearance	eries	1S Series with Safety Functionality	1S Series		
Type Built-in EtherCAT Communications Built-in EtherCAT Communications  Linear Type No	lodel		R88M-1A□/R88D-1SAN□-ECT		
Linear Type	ppearance				
100 VAC Applicable motor capacity/ force   200 W to 2.7 kW   50 W to 15 kW   50 W to 15 kW   600 W to 15 k	уре	Built-in EtherCAT Communications	Built-in EtherCAT Communications		
200 VAC Applicable motor capacity/ force	near Type	No	No		
### ### ### ### ### ### ### ### ### ##		No	50 W to 400 W		
Applicable servomotor		200 W to 2.7 kW	50 W to 15 kW		
Control mode         Position, speed and torque control         Position, speed and torque control           Safety approvals         -EN ISO 13849-1 (PLe/Cat.3) - EN G1508(SL3) - EN G1508(SL3) - EN G2061 (SIL CJ3) - EN G2061 (SIL CJ3) - EN G2061 (SIL CJ3) - EN G2061 (SIL CJ5) - EN G2061		750 W to 3 kW	600 W to 15 kW		
EN ISO 13849-1 (PLe/Cat.3)	pplicable servomotor	1S with Safety Functionality Servomotor	1S Servomotor		
F.N 61508(SIL3)   F.N 61508(SIL3)   F.N 61508(SIL3)   F.N 61508(SIL3)   F.N 61800-5-2(SIL3)   F.N 61800-5-2(	ontrol mode	Position, speed and torque control	Position, speed and torque control		
Appearance         3,000 r/min         3,000 r/min         2,000 r/min           Momentary maximum rotation speed         5,000 to 6,000 r/min         3,000 r/min         3,000 r/min           Rated torque         0.637 to 9.55 N·m         0.318 to 9.55 N·m         4.77 to 14.3 N·m           Capacity         200 W to 3 kW *1         50 W to 5 kW *3         400 W to 3 kW           Applicable servo drive         15 with Safety Functionality Drive         15 Servo Drive           Encoder resolution         20-bit absolute         23-bit absolute         23-bit absolute           Protective structure         IP67         IP67           Appearance         IP67         IP67           Rated rotation speed         1,500 r/min         1,500 r/min         1,000 r/min	afety approvals	• EN 61508(SIL3) • EN 62061(SIL CL3) • EN 61800-5-2(SIL3)	• EN61508 (SIL3/SIL2) • EN62061 (SIL3/SIL2)		
Rated rotation speed         3,000 r/min         2,000 r/min           Momentary maximum rotation speed         5,000 to 6,000 r/min         3,000 r/min           Rated torque         0.637 to 9.55 N·m         0.318 to 9.55 N·m         4.77 to 14.3 N·m           Capacity         200 W to 3 kW *1         50 W to 5 kW *3         400 W to 3 kW           Applicable servo drive         15 with Safety Functionality Drive         15 Servo Drive           Encoder resolution         20-bit absolute         23-bit absolute         23-bit absolute           Protective structure         IP67         IP67           Appearance         IP67         IP67    Rated rotation speed  1,500 r/min  1,000 r/min  1,000 r/min	ull closed loop	_	_		
Momentary maximum rotation speed         5,000 to 6,000 r/min         3,000 r/min           Rated torque         0.637 to 9.55 N·m         0.318 to 9.55 N·m         4.77 to 14.3 N·m           Capacity         200 W to 3 kW *1         50 W to 5 kW *3         400 W to 3 kW           Applicable servo drive         15 with Safety Functionality Drive         15 Servo Drive           Encoder resolution         20-bit absolute         23-bit absolute           Protective structure         IP67           Appearance         IP67           Rated rotation speed         1,500 r/min         1,500 r/min         1,000 r/min	ppearance				
Rated torque 0.637 to 9.55 N·m 0.318 to 9.55 N·m 4.77 to 14.3 N·m  Capacity 200 W to 3 kW *1 50 W to 5 kW *3 400 W to 3 kW  Applicable servo drive 15 Servo Drive 15 Servo Drive  Encoder resolution 20-bit absolute 23-bit absolute 23-bit absolute  Protective structure IP67 IP67  Rated rotation speed 1,500 r/min 1,500 r/min 1,000 r/min	ated rotation speed	3,000 r/min	3,000 r/min	2,000 r/min	
Rated torque  0.637 to 9.55 N·m  0.318 to 9.55 N·m  4.77 to 14.3 N·m  4.00 W to 3 kW  Applicable servo drive  15 with Safety Functionality Drive  15 Servo Drive  Encoder resolution  20-bit absolute  23-bit absolute  23-bit absolute  Protective structure  IP67  IP67  Appearance  Rated rotation speed  1,500 r/min  1,500 r/min  1,000 r/min		5,000 to 6,000 r/min	5,000 to 6,000 r/min	3,000 r/min	
Capacity 200 W to 3 kW *1 50 W to 5 kW *3 400 W to 3 kW  Applicable servo drive 15 with Safety Functionality Drive 15 Servo Drive  Encoder resolution 20-bit absolute 23-bit absolute 23-bit absolute  Protective structure IP67 IP67  Appearance IP67  Rated rotation speed 1,500 r/min 1,500 r/min 1,000 r/min		0.637 to 9.55 N·m	0.318 to 9.55 N·m	4.77 to 14.3 N·m	
Encoder resolution     20-bit absolute     23-bit absolute       Protective structure     IP67       Appearance     IP67       Rated rotation speed     1,500 r/min     1,500 r/min       1,500 r/min     1,000 r/min		200 W to 3 kW *1	50 W to 5 kW *3	400 W to 3 kW	
Encoder resolution     20-bit absolute     23-bit absolute       Protective structure     IP67       Appearance     IP67       Rated rotation speed     1,500 r/min     1,500 r/min       1,500 r/min     1,000 r/min		1S with Safety Functionality Drive	1S Servo Drive		
Appearance  Rated rotation speed  1,500 r/min  1,500 r/min  1,000 r/min			23-bit absolute	23-bit absolute	
Rated rotation speed         1,500 r/min         1,500 r/min         1,000 r/min	rotective structure	IP67	IP67		
	ppearance				
Momentary maximum rotation speed 3,000 r/min 2,000 to 3,000 r/min 2,000 to 3,000 r/min	ated rotation speed	1,500 r/min	1,500 r/min	1,000 r/min	
2,000 to 3,000 1/11111	lomentary maximum rotation speed	3,000 r/min	2,000 to 3,000 r/min	2,000 r/min	
Rated torque         9.55 to 19.1 N·m         25.5 to 95.5 N·m         8.59 to 28.7 N·m	ated torque	9.55 to 19.1 N·m	25.5 to 95.5 N·m	8.59 to 28.7 N·m	
Capacity         1.5 kW to 3 kW *2         4 to 15 kW         900 W to 3 kW	apacity	1.5 kW to 3 kW *2	4 to 15 kW	900 W to 3 kW	
Applicable servo drive 1S with Safety Functionality Drive 1S Servo Drive	pplicable servo drive	1S with Safety Functionality Drive	1S Servo Drive		
<b>Encoder resolution</b> 20-bit absolute 23-bit absolute 23-bit absolute	ncoder resolution	20-bit absolute	23-bit absolute	23-bit absolute	
Protective structure IP67 IP67	rotective structure	IP67	IP67		
Detailed specification Catalog 1838/1842 1821	etailed specification Catalog	1838/1842	1821		

<sup>\*1.</sup> The maximum capacity of the 200 V model is 2.6 kW. \*2. The maximum capacity of the 200 V model is 2.7 kW. \*3. The maximum capacity of the 200 V model is 4.7 kW.

# Motion

# 3G3MX2-A ... - V1 MX2-V1 Multi-function Compact Inverter

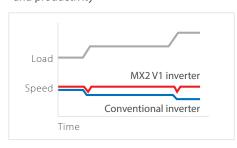
### Born to drive machines

# Torque control in open loop

- · Ideal for low to medium torque applications
- · Can replace a flux vector inverter or servo drive in suitable systems

### Quick response to load fluctuation

· Stable control without decreasing machine speed improves quality and productivity



# Safety inside

- · Conforms to safety norm ISO 1384901 Cat. 3 performance level PLd
- · 2 Safety inputs
- · External device monitoring (EDM)

### **Other Features**

- · Maximum applicable motor capacity: 15 kW
- · Double rating (CT: Heavy load/VT: Light load)
- · Permanent magnet motors
- · Drive Programming
- · Built-in brake control function



Ether CAT.

# 3G3RX2-□□□ RX2 High-function General-purpose Inverters

# Ether CAT

# Save energy and maximize performance with versatile inverter

- · Triple rating: Normal Duty (ND), Low Duty (LD), and Very Low Duty (VLD)
- · PM motor control helps save energy
- · Safety function IEC 61800-5-2 "Safe Torque Off (STO)" Conforms to machinery directive with ISO13849-1 (Category 4/PLe)
- · DriveProgramming allows simple sequence control without a PLC
- · EtherCAT communication using an optional communication unit provides highspeed communication for running and stopping, monitoring operating status, and changing various settings



Series		MX2 Series V1 type	RX2 Series
Model		3G3MX2-V1	3G3RX2
Appearance			
	Three-phase 200 V	0.1 to 15 kW(CT)	0.4 to 55 kW(ND)
Power supply	Three-phase 400 V	0.4 to 15 kW(CT)	0.4 to 132 kW(ND)
and capacity	Single-phase/three-phase 200 V	No	No
	Single-phase 200 V	0.1 to 2.2 kW(CT)	No
Control method	ds	· V/F control · Sensorless vector control	V/F control     Sensorless vector control     Vector control with a PG
	No. of multi-function I/O points	<ul><li>· 7 inputs</li><li>· 2 transistor outputs</li><li>· 1 relay output</li></ul>	· 11 inputs · 5 transistor outputs · 2 relay outputs
Input/ output	Analog I/O	· 2 inputs (0 to 10 V, 4 to 20 mA) · 1 output (0 to 10 V)	- 3 inputs (1)/(2) 0 to 10 V or 0 to 20 mA (3) -10 to 10 V · 2 outputs 0 to 10 V or 0 to 20 mA · 1 PWM voltage output
Braking		Braking resistor connection     Regenerative Braking Unit connection     Regenerative Braking Unit     + braking resistor connection	Braking resistor connection     200V (22 kW max.)     400V (37 kW max.)     Regenerative Braking Unit connection     Regenerative Braking Unit     + braking resistor connection
Frequency	Frequency setting range	0.1 to 400 Hz	0.1 to 400 Hz
rrequericy	Frequency output method	Line-to-line sine wave PWM	Line-to-line sine wave PWM
	Side-by-side mounting	Yes	No
Installation and wiring	Removable terminal block	No	Yes
	Power supply and motor wiring	Bottom wiring	Bottom wiring
	Multistep speed control	16 steps + jog	16 steps + jog
	Carrier frequency setting	2 to 15 kHz (default setting: 5 kHz)	2 to 15 kHz (default setting: 5 kHz)
	Torque assist function	Auto/manual torque assist	Auto/manual torque assist
	PID function	Yes	Yes
	Absolute value positioning	No	Yes
	Emergency shutoff	Yes	Yes
Main	0-Hz domain sensorless vector control	No	Yes
functions	Tripless function	Yes	Yes
	Momentary power interruption restart	Yes	Yes
	Multiple rating	Double ratings	Triple ratings
	Permanent magnet motor control	Yes	_
	Starting torque	200% at 0.5 Hz	· 200% at 0.3 Hz in open loop · Full torque at 0 Hz in closed loop
	PLC functionality (Drive Programming)	Provided	Provided
Communication	ns	Optional EtherCAT communication unit	Optional EtherCAT communication unit
Safety approva	ls	· ISO 13849-1 (Cat.3/PLd) · IEC 60204-1 Stop Category 0	· ISO13849-1 (Cat.4/PLe) · IEC 61800-5-2
Detailed specification	Catalog	1920	1921

# NX I/O-System

# Speed and accuracy for machine performance and information

Based on an internal high-speed bus running in synchronization with the EtherCAT network and using the time-stamp function, the NX I/O can be controlled with microsecond accuracy and with nanosecond resolution. The I/O range consists of over 100 models including position control, temperature inputs, and integrated safety. The EtherNet/IP unit with X Bus\*1 connectivity enables data transfer via EtherNet/IP as fast as 1 Gbps, achieving data utilization between machines or processes.



### Communications **IO-Link master EtherCAT slave** RFID Digital I/O Analog I/O coupler +/-10V voltage and 4-20 mA current · EtherCAT · Up to 4 IO-Link devices · Available as subsystem · Direct connection to 4, 8, 16, or 32 channels per · EtherNet/IP with one master controller on EtherCAT V680 RFID System input unit 2, 4, 8, 16, or 32 channels per · 2. 4 or 8 channels per input unit · 2 or 4 channels per output unit output unit (8 channels per Standard and high-performance models relay output unit) communications · Single-ended input and differential 16 channels per mixed I/O RS-232C or input models unit RS-422A/485 interface · Standard, high-speed, and time-stamp models High-speed analog input Units with Push-In · 4 channels per input unit Plus/MIL/Fujitsu/M3 Screw · Differential input connector · Sampling as fast as every 5 µs Load cell inputs Safety CPU **Temperature inputs** Temperature control **Position interface** · EN ISO13849-1(PLe/Safety · One load cell with one Thermocouple or RTD · 2 or 4 multi-input (thermocouple · Incremental and absolute Category 4), IEC 61508 (SIL3) inputs, 2 or 4 per unit and resistance thermometer) encoder support · Fastest conversion cycle certified Conversion time of 10 ms. channels per unit · Pulse output unit (line of 125 μs 60 ms or 250 ms · Conversion time of 50 ms driver output model) · Voltage output (for driving SSR) or linear current output · 1 CT input per channel Safety I/O **Heater burnput** Advanced temperature detection control · 4 CT sensor inputs and · 4 or 8 universal inputs · 4 or 8 safety input points per unit · 2 or 4 safety output points per unit 4 trigger outputs to drive (thermocouple, platinum resistance Free allocation of the safety I/O its SSRs thermometer, analog voltage, analog current) channels per unit on the internal high speed bus

Series	NX Series
Features	<ul> <li>Over 100 models including digital I/O, analog I/O, position interface, temperature inputs, temperature control, RFID, safety CPU, and safety I/O</li> <li>NsynX technology provides I/O response with less than 1 µs jitter</li> <li>Screwless terminal block, connector, and M3 screw types</li> <li>Up to 32 channels per digital input unit or output unit</li> </ul>
Appearance	
Туре	Modular I/O
Communications interface	EtherCAT
Number of connectable units	· 63 units max. · Input: 1,024 bytes max., output: 1,024 bytes max.
Unit types	Communications coupler, IO-Link master, serial communication, RFID, digital I/O, analog I/O, high-speed analog input, load cell input, safety I/O, safety CPU, temperature input, heater burnout detection, temperature control, position interface
Mounting	DIN track
Detailed specification Catalog	R183

 $<sup>^{\</sup>ast}$  See page 27 for more information on safety I/O.

Series	GX Series
Features	Detachable screw terminal block and e-CON connector types     Easy set-up: automatic and manual address setting
Appearance	
Туре	Block I/O
Communications interface	EtherCAT
Number of connectable units	One expansion unit can be connected with one digital I/O terminal (16 inputs + 16 outputs)
I/O types	Digital I/O, analog I/O, encoder input, IO-Link master, expansion unit
Mounting	DIN track
Detailed specification	Refer to your OMRON website.

# Safety

# NX-SL5/SL3/SI/SO Safety Control Unit

Integrated safety into machine automation

# Modular machines with individual CPU units

Safety is integrated via EtherNet/IP for safety communication between machines and EtherCAT for high-speed, high-precision fieldbus communication in a machine.

It is easy to set up motion or a robot, which are the key to quality and productivity enhancement, via one cable.



# Simple and flexible integration of safety

Flexible system lets you freely mix safety I/O units with standard NX I/O.



### Integration in One software, Sysmac Studio

Safety I/O wiring diagrams, safety circuit programs, and user-defined Function Blocks can be automatically generated, minimizing safety design errors. Simple Automatic Test using Offline Simulation is available. Online Functional Test ensures and maintains safety during machine commissioning and operation.



# Safety Controller

Product name	Safety CPU Unit		
Model	NX-SL5500/5700	NX-SL3300/3500	
Features	Two different networks, Safety over EtherCAT (FSoE) and EtherNet/IP (CIP Safety), in a single system	Integrated safety into machine automation through the use of Safety over EtherCAT (FSoE) protocol.	
Appearance	The state of the s		
Network	Safety over EtherCAT (FSoE), EtherNet/IP (CIP Safety)	Safety over EtherCAT (FSoE)	
Applicable standards	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508(SIL3), IEC/EN 62061(SIL CL3), IEC/EN 61131-2 , IEC 6132-3-1, IEC 61131-6	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508 (SIL3), EN 62061 (SIL CL3), IEC/EN 61131-2, IEC 6132-3-1	
Programming	· IEC 61131-3 standard · PLCopen Function Blocks for Safety		
Program capacity	2048 KB, 4096 KB	512 KB, 2048 KB	
Safety I/O connection	128/254	32/128	
Maximum number of safety I/O points	1024, 2032	256, 1024	
Units that can connect NX102 CPU Unit, Communication Control Unit		NX102 CPU Unit, EtherCAT Coupler Unit, EtherNet/IP Coupler Unit	
Detailed specification	Catalog: F104	Refer to your OMRON website.	

Product name	Safety Input Unit	Safety Output Unit
Model	NX-SIH400/SID800	NX-SOH200/SOD400
Appearance		
Applicable standards	EN ISO 13849-1 (PLe/Safety Category 4), IEC 61508(SIL3), IEC/EN 62061(SIL CL3), IEC/EN 61131-2, IEC 6132-3-1	
Number of safety input/ output points	4,8	2,4
Detailed specification	Refer to your OMRON website.	

# Vision

# Vision System

# Flexible solution for machine vision

The FH Vision System is optimized to detect the position and orientation of any object at high speed and with high accuracy. The built-in EtherCAT communications enable reliable and easy networking with motion control, increasing the overall machine performance. A flexible machine vision tailored for quality inspection.

# Advanced shape search technology

High-precision and robust positioning is possible even under the adverse conditions, such as changes in environments and materials.





Contrast



Chips





### **Unique lineup**

- ·The camera lineup includes up to 20.4 Mpix camera
- ·The MDMC light flexibly changes illumination colors and angles according to items to inspect



### **Multiple** inspection

- · Powerful 4-core i7 parallel processor
- · Up to 8 cameras per controller



# Al Scratch Detect Filter (Software sold separately)

The AI Scratch Defect Filter learns by means of images in which human inspectors noticed defects. Where as previous inspection methods found the unexpected size, shape or color of a particular defect to be a barrier to automation, AI successfully extracts abnormalities.







# FHV7 Smart Camera

# Designed for pre-alignment and appearance inspection

The FHV7 Smart Camera is an all-in-one camera with the functionalities of the high-spec FH Vision System packed in its compact, robust body that is easy to deploy. It offers the same operability as the FH Series, allowing for easy integration into even processes where it was previously difficult to install advanced vision systems.

# **IP67** waterproof structure

IP67 protection allows use in wet conditions, such as regular wash-downs at the sites where the cameras are installed.



# Advanced shape search technology

The shape search technology that provides the same level of performance as the FH Series has been implemented.

# Robust all-in-one camera for easy integration into machines



# **Autofocus lens**

The autofocus lens covers a focal length range from 59 to 2,000 mm\*. Even when products in different sizes are produced, the focus range can be changed easily by parameters. This feature eliminates mechanical operation for changeover during product replacement, leading to a simpler system with higher productivity.





Product nam	ie	Vision System		Smart Camera		
Series		FH Series		FHV7 Series		
Appearance						
	Processing speed * 1	***		**		
	No. of connectable cameras	8 max.		1		
Hardware	Resolution	0.4 million-pixel/2 million- pixel/4 million-pixel/5 million- pixel/12 million-pixel	5 million-pixel/20.4 million-pixel	0.4 million-pixel/1.6 million- pixel/3.2 million-pixel/5 million- pixel	6.3 million-pixel/12 million- pixel	
	Shutter method	Global shutter	Rolling shutter	Global shutter	Rolling shutter	
	Lens	Interchangeable (C mount, M42	mount)	Interchangeable (C mount)/autofocus (mechanical, liquid lens)		
	Light	External light connectivity/speci PS * 3)	al light connectivity (MDMC * 2,	Built-in light (white, red, infrared, multi-color)/external light connectivity/special light connectivity (MDMC * 2)		
Software	User interface	Flexible interface	Main screen Mea	isurement flow setting screen	Measurement condition setting screen	
Detailed specification	Catalog	Q197		Q264		

- f \* 1. The more starts, the higher the performance.
- ${\rm *2.\,Multi\text{-}Direction\,\,Multi\text{-}Color.\,The\,\,MDMC\,\,light\,\,can\,\,be\,\,adjusted\,\,to\,\,defects\,\,by\,\,freely\,\,combining}$ the illumination directions, colors, and light intensities.
- \* 3. Photometric Stereo.

# Sensing

# ZW-8000/7000 Confocal Fiber Displacement Sensor

Measure anything from anywhere The most reliable in-line measurements

The ZW-8000 Series provides high-precision in-line measurements of rattling or inclined shiny, thin, or minute parts. The ZW-7000 Series provides ultra-high-speed, stable measurements of diffuse reflective objects during movement. These sensors help increase quality inspection accuracy and reduce inspection time.



### Reliable measurements for any material and surface types

The white light confocal principle allows a continuous measurement of object in any mixed conditions such as mirror, coarse, transparent, curved, or narrow areas without stopping the sensor head.



- · Angle characteristic: ±25° for shiny surfaces
- $\cdot$  Linearity for different materials:  $\pm 0.3~\mu m$
- · Minimum sampling period: 20 µs
- · Minimum spot diameter: 4 µm

Note: Specifications differ among models. Please ask Omron sales representative for details.

# E3NX/E3NC/E9NC Series N-Smart Series

# Various sensors connected over EtherCAT

The N-Smart lineup of next-generation fiber sensors, laser sensors and contact sensors will quickly solve your problems and therefore maximize uptime and minimize downtime with optimum cost performance.



### **Features**

- Ultra-easy Advanced Smart Tuning with the push of a button
- More stable detection of high-speed workpieces
- Predictive maintenance to reduce downtime
- · Highly visible white LED display
- E3NX-FA has 1.5x the sensing distance of conventional amplifiers\*

\* Compared with E3X-HD

Product nan	ne	Confocal Fiber Displacement Sensor				
Series		ZW-8000 Series	ZW-7000 Series	ZW-5000 Series		
Feature		For measurements of rattling or inclined "transparent objects or mirror surfaces" such as thin film sheets or glass	For accurate shape measurements of "coarse surfaces" while the sensor head is moving	Bring the benefits of the white light confocal principle to production lines		
Appearance						
Measurement method		White light confocal principle				
Measuring range		Min: 7±0.3 mm, Max: 30±2 mm				
Static resolution		0.002 to 0.016 μm				
Linearity		±0.3 to ±3.0 µm				
Spot diameter		4 to 11 μm	50 to 190 μm	9 to 20 μm		
Measurement cycle		60 to 7500 μs	20 to 400 μs	80 to 1600 μs		
Detailed specification	Catalog	Q250				
	Web	Refer to your OMRON website.				

Product name		Fiber Sensor/Laser Sensor/Proximity Sensor/Contact Sensor				
Series		N-Smart Series	E3X			
Feature		Connect fiber, laser and contact sensors to EtherCAT at low initial cost	Easily connect fiber sensors to EtherCAT			
Appearance						
Network specification		EtherCAT communication unit	EtherCAT communication unit			
Sensor Communica- tions Units		E3NW-ECT/DS	E3X-ECT			
Connectable sensor amplifier units		Fiber Sensor E3NX-FA0 E3NX-CA0 Laser Sensor E3NC-LA0 E3NC-SA0 Contact Sensor E9NC-TAO loT Status Monitoring Amplifier E9NC-AAO/VA0	Fiber Sensor E3X-HD0			
Maximum number of connectable sensors		30	30			
Detailed specification	Catalog	E3NW: E418 E3NX-FA: E418 E3NX-CA: Y216 E9NC-T: E434 E9NC-AA/VA: E474	_			
	Web	Refer to your OMRON website.				

# Robot

# iX3/iX4, eCobra/i4H, Viper Parallel Robot, SCARA Robot, Articulated Robot with EtherCAT (Connectable to NJ501-R)

Robots for flexible production lines

Omron's parallel, SCARA, and articulated robots are designed to be directly controlled by the NJ501-R Robot Integrated Controller that is connected to the robots via EtherCAT.

# **Parallel robots**

The Hornet and Quattro are parallel robots ideal for use in the food and beverage, pharmaceutical, and healthcare industries.

The iX4 that is a four-axis parallel robot with a high payload capacity achieves high speed and high precision.

- · Fast and high-precision conveyance and assembly
- · Supports fast Pick & Place on a fast conveyor
- · Maximum working range: 1130, 1300, and 1600 mm models



### **SCARA** robots

High-performance four-axis SCARA robots are ideal for mechanical assembly, material handling, packaging, machine tending, and screw driving.

Table/floor or Inverted mounting models are available.

- · High repeatability suitable for material handling and precision assembly
- · Reach: i4H: 650, 750, and 850 mm models eCobra: 600 and 800 mm models



# **Articulated robots**

Six-axis articulated robots are ideal for mechanical assembly, material handling, packaging, and palletizing.

- · Diagnostics display enables faster trouble shooting
- · High accuracy, superior slow-speed following, and easy calibration
- · Reach: 653 and 855 mm models



Series		iX3	iX4	eCobra
Feature		Parallel robot ideal for use in the food and beverage, pharmaceutical, and healthcare industries	Four-axis parallel robot achieves high speed and high precision	Mid-size/large SCARA robot for precision machining, assembly, and material handling
Appearance				
Robot type		Parallel robot	Parallel robot	SCARA robot
Number of axes		3, 4	4	4
Mounting		Inverted	Inverted	Table/Floor
Payload capacity		3 kg (8 kg: without rotation axis)	· Quattro 650 6 kg (No rotation: 15 kg) · Quattro 800 4 kg (No rotation: 10 kg)	5.5 kg
Working volume (radius)		565 mm	650 to 800 mm	_
Reach		_	_	600 to 800 mm
Position repeatab	oility	±0.10 mm	±0.10 mm	±0.017 mm
Protection/ Cleanroom classes	Specifications	IP67: arms and platform IP65: underside of robot IP20: topside of robot	· H type IP67: arms and platform IP65: underside of robot IP20: topside of robot · HS type IP67: arms and platform IP66: robot base	IP20
	Option	IP65: topside of robot (with optional cover)	H type IP65: topside of robot (with optional cover)	- eCobra 600     Class10 Cleanroom model     - eCobra 800     IP65, Class10 Cleanroom model
Detailed Specification Catalog		1822		

Series		i4H	i4H Inverted	Viper
Feature		Mid-size/large SCARA robot for precision machining, assembly, and material handling	Overhead-mount mid-size/large SCARA robot for precision machining, assembly, and material handling	Articulated robot for machining, assembly, and material handling
Appearance				
Robot type		SCARA robot	SCARA robot	Articulated robot
Number of axes		4	4	6
Mounting		Table/Floor	Inverted	Table/Floor/Inverted
Payload capacity		15 kg	15 kg	5 kg
Working volume	(radius)	_	_	_
Reach		650 to 850 mm	650 to 850 mm	635 to 855 mm
Position repeatability		XY: i4H 650 ±0.015 mm, i4H 750/850 ±0.025 mm Z: ±0.015 mm $\theta$ : ±0.005°		±0.02 to 0.03 mm
Protection/ Cleanroom classes	Specifications	IP20	IP20	IP40
	Option	ISO4, IP65, Class10 Cleanroom model	ISO4, IP65, Class10 Cleanroom model	IP54: robot main body IP65: robot joints (J4, J5, J6) Class10 Cleanroom model
Detailed specification	Catalog	1822		

# Service and support



# **COMPETENCE**



### Design

Our wi de net work of machine automation specialists will help you to select the right automation architecture and products to meet your requirements. Our flat structure based on expert-to-expert contact ensures that you will have ONE accountable and responsible expert to deal with on your complete project.



# **Proof of concept**

As your project matures make use of our Automation centers to test and catch-up with technology trends in motion, robotics, networking, safety, quality control etc. and to interface, test and validate your complete system with our new machine network (EtherCAT) and factory network (EtherNet/IP).

We will assign a dedicated application engineer to assist with initial programming and proof testing of the critical aspects of your automation system. Our application engineers have indepth expertise in and knowledge of networks, PLCs, motion, safety and HMIs when applied to machine automation.





# alt; atc

# **CONFIDENCE**

For the most recent information, refer to your OMRON website.

# 日 州 国 価 商 JAPAN PASSPORT

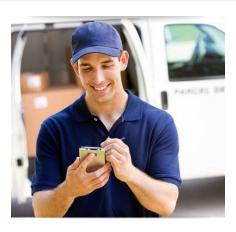
# Development

During your prototyping phase you will need flexibility in technical support, product supply and exchange. We will assign an inside sales contact to help you source the correct products fast during your prototyping phase.

# Commissioning

With our world-wide network for service and support the export of your product is made simple, we will support you on-site with your customer, anywhere in the world. We can arrange a liaison sales engineer to facilitate training, spare parts supply or even machine commissioning. All this in a localised language with localised documentation - giving you complete peace of mind.

# **ASSURANCE**



# Serial production

As your production increases we will engage in supplying you within 24hrs and repairing within 3 days. All our products are global products meeting global standards - CE, cULus, NK, LR -

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